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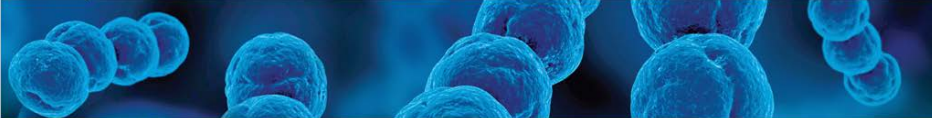


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### Author Activities

MS Number	Title & Authors	Additional Files	Status
 8760215.v1 (Research Article)	 Gait Tracking Control of Quadruped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity $H_\infty$ Robust Control Petrus Sutiyasadi, and M. Parnichkun		Under Review

Mar 6, 2106

Dear Dr. Sutyasadi,

This is regarding manuscript 8760215 titled "Gait Tracking Control of Quadraped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity  $H^\infty$  Robust Control." I have noticed that the "Conflict of Interest" statement is missing.

According to our policy, a competing interest exists when professional judgment concerning the validity of research is influenced by a secondary interest such as financial gain. We require that our authors reveal any possible conflict of interest in their submitted manuscripts. If there is no conflict of interest, authors should state that "The author(s) declare(s) that there is no conflict of interest regarding the publication of this article." Otherwise, please send me an updated PDF file of your manuscript including a detailed disclosure in a Conflict of Interest section.

Also, please confirm that the mentioned received grants, scholarships, or funding in the "Acknowledgments" section, do not lead to any conflicts of interest regarding the publication of this manuscript.

I look forward to receiving your reply.

Best regards,

Nouran

March 7, 2016

Please find attached the updated PDF file of the manuscript titled “Gait Tracking Control of Quadruped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity  $H_\infty$  Robust Control”.

I hereby also declare and confirm that there is no conflict of interests regarding the publication of this paper and the received funding or any party mentioned in the “Acknowledgement” section. Thank you.

Best Regards,  
Petrus Sutyasadi

16 June 2016

Dear Dr. Sutyasadi,

Following the review of Research Article titled "Gait Tracking Control of Quadraped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity  $H^\infty$  Robust Control" by Petrus Sutyasadi and M. Parnichkun, I recommend that it should be revised taking into account the changes requested by the reviewer(s). Since the requested changes are major, the revised manuscript will undergo a second round of review by the same reviewer(s). Please login to the Manuscript Tracking System to read the submitted review report(s) and submit the revised version of your manuscript no later than July 14, 2016.

To submit the revised version of your manuscript, please access "Author Activities" in your account and upload the PDF file of your revised manuscript. Also, please submit your replies to the comments of the reviewer(s) as an additional PDF file.

Best regards,

Carlos-Andrés García  
[carlosandres.garcia@uca.es](mailto:carlosandres.garcia@uca.es)

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




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 8760215.v1 (Research Article)	 Gait Tracking Control of Quadraped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity $H^\infty$ Robust Control Petrus Sutyasadi, and M. Parnichkun		Major Revision Required

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## 8760215.v1 (Research Article)

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<b>Title</b>	 Gait Tracking Control of Quadraped Robot Using Differential Evolution Based Structure Specified Mixed Sensitivity $H_{\infty}$ Robust Control
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<b>Issue</b>	Regular
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<b>Author(s)</b>	  Petrus Sutiyasadi,   M. Parnichkun
<b>Editor</b>	  Carlos-Andrés Garcia
<b>Status</b>	Major Revision Required

No.	Review Report
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