petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Manuscript ID IR-06-2019-0135

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 20 June 2019 at 15:20
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

20-Jun-2019

Dear Dr. Sutyasadi,

Your manuscript entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" has been successfully submitted online and is presently being given full consideration for publication in Industrial Robot.

Your manuscript ID is IR-06-2019-0135.

Please mention the above manuscript ID in all future correspondence or when calling the office for questions. If there are any changes in your street address or e-mail address, please log in to ScholarOne Manuscripts at https://mc.manuscriptcentral.com/indrobot and edit your user information as appropriate.

You can also view the status of your manuscript at any time by checking your Author Centre after logging in to https://mc.manuscriptcentral.com/indrobot.

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If you would like to publish your article open access please contact openaccess@emeraldgroup.com

Thank you for submitting your manuscript to Industrial Robot.

Yours sincerely,
Industrial Robot Editorial Office

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 27 June 2019 at 19:43
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

27-Jun-2019
Dear Author(s)
It is a pleasure to inform you that your manuscript titled Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control (IR-06-2019-0135) has passed initial screening and is now awaiting reviewer selection. The manuscript was submitted by Dr. Petrus Sutyasadi with you listed as a co-author. As you are listed as a co-author please log in to https://mc.manuscriptcentral.com/indrobot and check that your account details are complete and correct, these details will be used should the paper be accepted for publication.
Yours sincerely,
Clive Loughlin
Editorial Assistant, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Re: Industrial Robot

1 message

Emerald <emerald@coastlinetechnology.com> 20 August 2019 at 16:33
To: peter@pmsd.ac.id

Hi Petrus,

Sorry we are taking some time to review your paper. I have been struggling to find reviewers and have just invited another 6.

I have one favourable review but do need to obtain further reviews.

Can you please suggest additional Reviewers who might be willing and able to provide and unbiased review?

I hope to be able to make a decision on your paper within 2 weeks.

Best wishes,

Clive

Dr Clive Loughlin CEng MIET - Editor Industrial Robot
Email emerald@coastlinetechnology.com

Manuscripts are submitted online via Manuscript Central:
Web http://mc.manuscriptcentral.com/automation

On 15 Aug 2019, at 10:29, Industrial Robot <onbehalfof@manuscriptcentral.com> wrote:

15-Aug-2019

IR-06-2019-0135 - Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control

Dear Dr. Loughlin:

I would like to ask about the progress of my manuscript sent to Industrial Robot Journal.
Thank you.

Best wishes,

Petrus

Dr. Petrus Sutyasadi

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 12 September 2019 at 20:31
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

12-Sep-2019

Dear Author(s),

It is a pleasure to inform you that all required reviews have been received for your manuscript entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" and that your paper is now awaiting an Editor Decision.

Yours sincerely,
Clive Loughlin
Editorial Assistant, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Sutyasadi - Industrial Robot - Decision on Manuscript ID IR-06-2019-0135

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 12 September 2019 at 20:32
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

12-Sep-2019

Dear Dr. Sutyasadi,

Manuscript ID IR-06-2019-0135 entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" which you submitted to Industrial Robot, has been reviewed. The comments of the reviewer(s) are included at the bottom of this letter.

The reviewer(s) have recommended major revisions to the submitted manuscript, before it can be considered for publication. Therefore, I invite you to respond to the reviewer(s)' comments and revise your manuscript.

Author Guide:
https://mc.manuscriptcentral.com/societyimages/indrobot/How%20to%20publish%20in%20IR-SR.pdf

To revise your manuscript, log in to https://mc.manuscriptcentral.com/indrobot and enter your Author Centre, where you will find your manuscript title listed under "Manuscripts with Decisions." Under "Actions," click on "Create a Revision." Your manuscript number has been appended to denote a revision.

You will be unable to make your revisions on the originally submitted version of the manuscript. Instead, revise your manuscript using a word processing program and save it on your computer. Please also highlight the changes to your manuscript within the document by colouring the major changes in RED. Please do NOT use the track changes mode in MS Word as this makes re-review difficult.

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IMPORTANT: Your original files are available to you when you upload your revised manuscript. Please delete any redundant files before completing the submission.

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Once again, thank you for submitting your manuscript to Industrial Robot and I look forward to receiving your revision.

Best wishes,
Yours sincerely,

Clive

Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

Emerald has partnered with Peerwith to provide authors with expert editorial support, including language editing and translation, visuals, and consulting. If your article was rejected, or had major revisions requested on the basis of the language or clarity of communication, you might benefit from a Peerwith expert's input. For a full list of Peerwith services, visit: https://authorservices.emeraldpublishing.com/
Please note that there is no obligation to use Peerwith and using this service does not guarantee publication.

Reviewer(s)' Comments to Author:

Reviewer: 1

Comments:
Add more recent work or publications to strengthen the background.
Add future study or some suggestions in the conclusion.

Additional Questions:
1. Originality: Does the paper contain new and significant information adequate to justify publication?: New concept that the paper tries to present is FRP algorithm. A balancing strategy for a quadruped.
Another significant information is the proposed controller which is a low order H2/H infinity Robust controller that applicable to small embedded system ans its synthesis method.

2. Relationship to Literature: Does the paper demonstrate an adequate understanding of the relevant literature in the field and cite an appropriate range of literature sources? Is any significant work ignored?: The paper cites relevant literature sources. However, the paper needs to add more recent works to strengthen the background

3. Methodology: Is the paper's argument built on an appropriate base of theory, concepts, or other ideas? Has the research or equivalent intellectual work on which the paper is based been well designed? Are the methods employed appropriate?: The concept and the theory are presented in order, make it easy to understand and duplicate.

4. Results: Are results presented clearly and analysed appropriately? Do the conclusions adequately tie together the other elements of the paper?: Simulation and experiment results are presented clearly. The paper compared several methods to show the benefit of the proposed algorithm. The analysis shows the advantages
and limitation of the proposed method. Everything is concluded properly except there is no future study or any suggestion to improve the research

5. Practicality and/or Research implications: Does the paper identify clearly any implications for practice and/or further research? Are these implications consistent with the findings and conclusions of the paper?: The practical implication is shown that the low order H2/H infinity. Robust controller has been successfully embedded into small microcontroller to control the quadruped robot reaching the FRP and maintaining its balance.
All are consistent with the findings and conclusions.

6. Quality of Communication: Does the paper clearly express its case, measured against the technical language of the field and the expected knowledge of the journal's readership? Has attention been paid to the clarity of expression and readability, such as sentence structure, jargon use, acronyms, etc.: The paper clearly expresses its case. It explains in detail the problems and the proposed solutions. Algorithm derivation and controller synthesis are well explained. This makes a good material for the journal's readers.
The paper and sentence structure are easy to understand.

Reviewer: 2

Comments:
The authors adopted FRP from biped robot technology and applied it to the quadruple push recovery control. And to move the quadruple robot robustly to the FRP point, they designed H-infinity/2 controller using particle swarm optimization. I give this manuscript reject and resubmit regarding some points. The points are listed below...

1. Lack of walking trajectory generation of quadruple. They must add the walking trajectory generation method and visualization.

2. In section 4.1, there are no thorough notations. First, the authors change Fig. 4~6 to quadruple picture and re-build the variable notations thoroughly. Even though FRP is from biped robot technology, they had the responsibility to visualize it to the quadruple. I had the difficulty to understand the Fig. 4~5 and adopt it to quadruple. The authors better omit all the biped picture and replace it to the quadruple pictures.(the notations, equations must be fully understandable to the reader.)

3. Section 4.1 Fig. 7. Fig. 4~7 and the variable notations must be consistent.

4. 4.2 Eqs.(27). The authors claimed that they modeled the quadruple to the compass biped model. I don't think that this makes sense. If they have, they must clearly state the reason and visualize it by overlapping the compass picture and quadruple picture. And all the variables in Eqs. are clearly explained. For example, tau in Eqs. (27).

5. Fig. 23. The authors must represent the experimental results without push recovery.

Additional Questions:
1. Originality: Does the paper contain new and significant information adequate to justify publication?: The manuscript adopted FRP from the biped robot technology and applied to quadrupled. And designed H-infinity/2 controller to swiftly move the quadrupled to FRP point. I think that the manuscript has its own originality even though used FRP.

2. Relationship to Literature: Does the paper demonstrate an adequate understanding of the relevant literature in the field and cite an appropriate range of literature sources? Is any significant work ignored?: In the introduction, there are some quadruple references and H-infinity controller references. However, the authors needs a more through reference analysis about quadruple push recovery.

3. Methodology: Is the paper's argument built on an appropriate base of theory, concepts, or other ideas? Has the research or equivalent intellectual work on which the paper is based been well designed? Are the methods employed appropriate?: The methodology is well organized.

4. Results: Are results presented clearly and analysed appropriately? Do the conclusions adequately tie together the other elements of the paper?: The authors showed an appropriate experimental results.

5. Practicality and/or Research implications: Does the paper identify clearly any implications for practice and/or further research? Are these implications consistent with the findings and conclusions of the paper?: The paper has implications for practice

6. Quality of Communication: Does the paper clearly express its case, measured against the technical language of the field and the expected knowledge of the journal's readership? Has attention been paid to the clarity of expression and readability, such as sentence structure, jargon use, acronyms, etc.: The English is well written.

Deadline:
11-Nov-2019

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 14 October 2019 at 21:45
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

14-Oct-2019

Dear Author(s),

It is a pleasure to inform you that your manuscript titled Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control (IR-06-2019-0135.R1) has passed initial screening and is now awaiting reviewer invitation.

The manuscript was submitted by Dr. Petrus Sutyasadi with you listed as a co-author.

As you are listed as a co-author, if you have not already done so please log in to https://mc.manuscriptcentral.com/indrobot and check that your account details are complete and correct, these details will be used should the paper be accepted for publication.

Yours sincerely,
Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Manuscript ID IR-06-2019-0135.R1

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 14 October 2019 at 21:46
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

14-Oct-2019

Dear Dr. Sutyasadi,

Your manuscript entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" has been successfully submitted online and is presently being given full consideration for publication in Industrial Robot.

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Please mention the above manuscript ID in all future correspondence or when calling the office for questions. If there are any changes in your street address or e-mail address, please log in to ScholarOne Manuscripts at https://mc.manuscriptcentral.com/indrobot and edit your user information as appropriate.

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Thank you for submitting your manuscript to Industrial Robot.

Yours sincerely,
Industrial Robot Editorial Office

petrus sutyasadi <peter@pmsd.ac.id>

Sutyasadi - Industrial Robot - Decision on Manuscript ID IR-06-2019-0135.R1

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 9 January 2020 at 19:03
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

09-Jan-2020

Dear Dr. Sutyasadi,

Manuscript ID IR-06-2019-0135.R1 entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" which you submitted to Industrial Robot, has been reviewed. The comments of the reviewer(s) are included at the bottom of this letter.

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Our Author Guide 'How to publish in Industrial Robot' can be found here:
https://mc.manuscriptcentral.com/societyimages/indrobot/How%20to%20publish%20in%20IR-SR.pdf

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Once again, thank you for submitting your manuscript to Industrial Robot and I look forward to receiving your revision.

Best wishes,
Yours sincerely,

Clive

Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

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Please note that there is no obligation to use Peerwith and using this service does not guarantee publication.

Reviewer(s)' Comments to Author:

Reviewer: 1

Recommendation: Minor Revision

Comments:
The authors followed my previous review comments. It seems to be a good shape of manuscript. However, there are some issues to address on.

1. Make Fig. 6, 7, 8 to one picture. And define the parameters(theta_ABC, omega_ABC etc.) to the one picture. One mass with two legs pictures representing initial, impact-, impact+, final status is sufficient to represent the FRP status of the biped(quadruple).

2. Add arrows which represents the swing motion of the quadruple and leg movement in Fig. 5 for clearness.

3. Add the objective of mixed-H_infinity/H2 controller in the introduction (To robustly track the desired joint angle etc.)

Additional Questions:
1. Originality: Does the paper contain new and significant information adequate to justify publication?: The authors applied FRP to quadruple push recovery strategy and H-infinity/2 mixed controller to make the each quadruple joint robustly track the reference trajectory and tuned the controller by PSO method and verified the proposed method by real quadruple experiment. I think even though the authors did not suggested their own method, it deserves to be considered in the journal publication for its applicability and simulation/experiment completeness.

2. Relationship to Literature: Does the paper demonstrate an adequate understanding of the relevant literature in the field and cite an appropriate range of literature sources? Is any significant work ignored?: I think that the paper listed the relevant literature in the field.

3. Methodology: Is the paper's argument built on an appropriate base of theory, concepts, or other ideas? Has the research or equivalent intellectual work on which the paper is based been well designed? Are the methods employed appropriate?: The methodology is good. They followed theory-simulation-

experiment validation procedures.

4. Results: Are results presented clearly and analysed appropriately? Do the conclusions adequately tie together the other elements of the paper?: The results are concise and clear.

5. Practicality and/or Research implications: Does the paper identify clearly any implications for practice and/or further research? Are these implications consistent with the findings and conclusions of the paper?: The paper identified clearly implications for practice. However, there seems to be no further research direction.

6. Quality of Communication: Does the paper clearly express its case, measured against the technical language of the field and the expected knowledge of the journal's readership? Has attention been paid to the clarity of expression and readability, such as sentence structure, jargon use, acronyms, etc.: English used in the manuscript is good.

Deadline:
08-Feb-2020

petrus sutyasadi <peter@pmsd.ac.id>

Sutyasadi - Industrial Robot - Decision on Manuscript ID IR-06-2019-0135.R1

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 9 January 2020 at 19:03
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

09-Jan-2020

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Best wishes,
Yours sincerely,

Clive

Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

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Please note that there is no obligation to use Peerwith and using this service does not guarantee publication.

Reviewer(s)' Comments to Author:

Reviewer: 1

Recommendation: Minor Revision

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1. Make Fig. 6, 7, 8 to one picture. And define the parameters(theta_ABC, omega_ABC etc.) to the one picture. One mass with two legs pictures representing initial, impact-, impact+, final status is sufficient to represent the FRP status of the biped(quadruple).

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Deadline:
08-Feb-2020

petrus sutyasadi <peter@pmsd.ac.id>

IR - Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control, is now published online.

1 message

adminTrackit@emeraldpublishing.com <adminTrackit@emeraldpublishing.com> 9 March 2020 at 20:45
To: peter@pmsd.ac.id

09-Mar-2020

IR - Industrial Robot: the international journal of robotics research and application

Emerald Insight Date: 09-Mar-2020

I am pleased to inform you that Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control of *Industrial Robot: the international journal of robotics research and application* has been published on Emerald Insight.

Should you have any queries please do not hesitate to contact the Production Department.

Best Wishes,

H.Eustace

Emerald Production Department

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

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09-Jan-2020

Dear Author(s),

It is a pleasure to inform you that all required reviews have been received for your manuscript entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" and that your paper is now awaiting an Editor Decision.

Yours sincerely,
Clive Loughlin
Editorial Assistant, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

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Yours sincerely,
Clive Loughlin
Editorial Assistant, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Author update

2 messages

Industrial Robot <onbehalfof@manuscriptcentral.com> 22 January 2020 at 12:12
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

22-Jan-2020

Dear Author(s),

It is a pleasure to inform you that your manuscript titled Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control (IR-06-2019-0135.R2) has passed initial screening and is now awaiting reviewer invitation.

The manuscript was submitted by Dr. Petrus Sutyasadi with you listed as a co-author.

As you are listed as a co-author, if you have not already done so please log in to https://mc.manuscriptcentral.com/indrobot and check that your account details are complete and correct, these details will be used should the paper be accepted for publication.

Yours sincerely,
Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

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Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

22-Jan-2020

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Editorial Assistant, Industrial Robot
emerald@coastlinetechnology.com

petrus sutyasadi <peter@pmsd.ac.id>

Industrial Robot - Manuscript ID IR-06-2019-0135.R2

1 message

Industrial Robot <onbehalfof@manuscriptcentral.com> 22 January 2020 at 12:12
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id

22-Jan-2020

Dear Dr. Sutyasadi,

Your manuscript entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" has been successfully submitted online and is presently being given full consideration for publication in Industrial Robot.

Your manuscript ID is IR-06-2019-0135.R2.

Please mention the above manuscript ID in all future correspondence or when calling the office for questions. If there are any changes in your street address or e-mail address, please log in to ScholarOne Manuscripts at https://mc.manuscriptcentral.com/indrobot and edit your user information as appropriate.

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Thank you for submitting your manuscript to Industrial Robot.

Yours sincerely,
Industrial Robot Editorial Office

petrus sutyasadi <peter@pmsd.ac.id>

Sutyasadi - Industrial Robot - Decision on Manuscript ID IR-06-2019-0135.R2

3 messages

Industrial Robot <onbehalfof@manuscriptcentral.com> 22 January 2020 at 20:55
Reply-To: emerald@coastlinetechnology.com
To: peter@pmsd.ac.id, petrussutyasadi@yahoo.co.id, manukid@ait.ac.th

22-Jan-2020

Dear Sutyasadi, Petrus; Parnichkun, Manukid

It is a pleasure to accept your manuscript IR-06-2019-0135.R2, entitled "Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H∞ Control" in its current form for publication in Industrial Robot. Please note, no further changes can be made to your manuscript.

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Thank you for your contribution. On behalf of the Editors of Industrial Robot, we look forward to your continued contributions to the Journal.

Yours sincerely,

Dr. Clive Loughlin
Editor, Industrial Robot
emerald@coastlinetechnology.com

Manukid Parnichkun <manukid@ait.asia> 23 January 2020 at 14:24
To: petrus sutyasadi <peter@pmsd.ac.id>

Dear Dr. Petrus,

Congratulations! The paper is accepted. Do I need to fill copyright transfer agreement also?

Best regards,
Manukid
[Quoted text hidden]

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petrus sutyasadi <peter@pmsd.ac.id> 23 January 2020 at 16:03
To: Manukid Parnichkun <manukid@ait.asia>

Dear Prof. Manukid,

Thank you very much. I think, according to the email above, all authors are requested to complete the CTA. All authors also may update/correct the full contacts detail there. We may use our recently updated ORCID data. Sorry for the inconvenience from the editor procedures.

I'm also sorry for the delay in processing this second paper. This is the fourth journal that I have tried since I went back to Indonesia. Journal of Robotics and Mechatronics from Fuji Technology Press and Artificial Life and Robotics from Springer both of them asked for publication fee more than 150000 JPY. They do not mention the fee in their website. I withdrew my submission from both of the journals. The third journal was International Journal of Robotics and Automation. This journal asked to reduce the pages to much, almost 40%, which is very difficult to do. Then lastly is this Industrial Robot from Emerald. The SNIP is not bad 1,022, but their internationality (SJR International Collaboration) is reducing.

Once again thank you Prof. Manukid for all your support in doing the thesis last time, so this paper is possible to be published.

Best regards,
Petrus
[Quoted text hidden]

petrus sutyasadi <peter@pmsd.ac.id>

Advance notification: Proof for 'Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control'

1 message

manuscriptadmin@emeraldinsight.com <manuscriptadmin@emeraldinsight.com> 13 February 2020 at 22:31
To: peter@pmsd.ac.id

Dear Petrus Sutyasadi,

Thank you for publishing with Emerald.

Your article which will publish in Industrial Robot: the international journal of robotics research and application has been received for production.

Article Title: Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control
Article Id: 642141

The proof of your article will be sent to you for review within the next 8 to 10 days.

Once you've received your proof, please review it and submit any corrections within 5 working days of receipt. If we do not receive any corrections from you, we will assume that no changes are required and proceed with publication.

You will receive a link via email to access your proof, which will be supplied in PDF format.
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Kind regards,

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petrus sutyasadi <peter@pmsd.ac.id>

Notification: Your proof is now ready for review and submission 'Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control'

1 message

manuscriptadmin@emerald.com <manuscriptadmin@emerald.com> 21 February 2020 at 21:32
To: peter@pmsd.ac.id

Dear Petrus Sutyasadi,

Thank you for publishing with Emerald.

The proof of your article which will publish in Industrial Robot: the international journal of robotics research and application is now available for review.

Article Title: Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control
Article Id: 642141

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Please return the corrected proof by Wed February 26, 2020 09:32 AM, EST. If we do not receive any corrections from you we will assume that no changes are required and we will proceed with publication.

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petrus sutyasadi <peter@pmsd.ac.id>

Reminder: Your proof is ready for review and submission 'Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control'

1 message

manuscriptadmin@emerald.com <manuscriptadmin@emerald.com> 24 February 2020 at 21:31
To: peter@pmsd.ac.id

Dear Petrus Sutyasadi,

We would like to thank you again for choosing to publish with Emerald.

We do like to give you the opportunity to proof and correct your article before publication. However, we have not yet received corrections for your article which will publish in Industrial Robot: the international journal of robotics research and application.

To avoid further delay in publication of the issue, corrections must be received by Wed February 26, 2020 09:32 AM, EST.

Article Title: Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control
Article Id: 642141

You have been sent this proof as the Corresponding Author. Please note that your co-author/s will not receive a proof of this article, so only corrections submitted via this proof will be incorporated into the final published version of your article. Please ensure all author names and affiliations are correct before returning the proof.

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petrus sutyasadi <peter@pmsd.ac.id>

Your article has been assigned to an issue

1 message

Emerald <replies@emeraldinsight.com> 18 May 2020 at 19:48
Reply-To: Emerald Publishing Limited <reply-fe9411767566027971-409_HTML-438410319-7214338-2@email.emeraldinsight.com>
To: peter@pmsd.ac.id

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Dear Dr. Sutyasadi,

We're pleased to let you know that your paper '**Push Recovery Control of Quadruped Robot Using Particle Swarm Optimization Based Structure Specified Mixed Sensitivity H2/H8 Control**' has now been assigned a volume and page numbers.

You can find lots of information including **copyright information** and contacts on our **author pages**.

Kind regards

The Emerald Team

Together we can make a Real Impact.